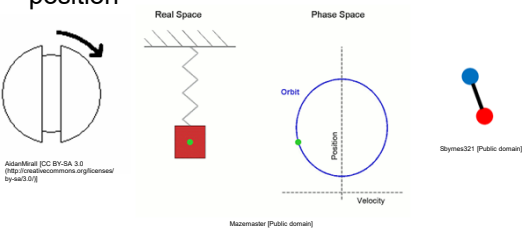


Simple Harmonic Motion

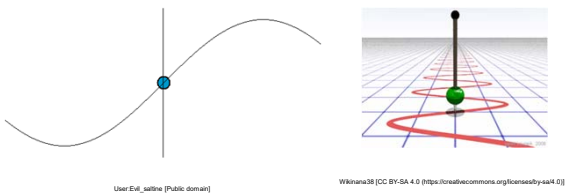
Oscillations

- Repetitive (periodic) motion
- Object moves around an equilibrium position



Simple Harmonic Motion

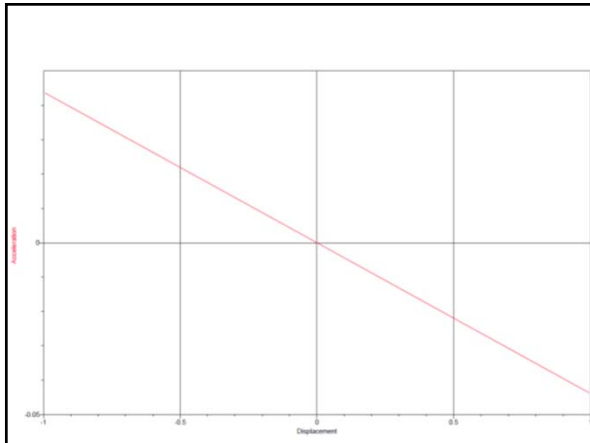
- Periodic motion that is sinusoidal in nature



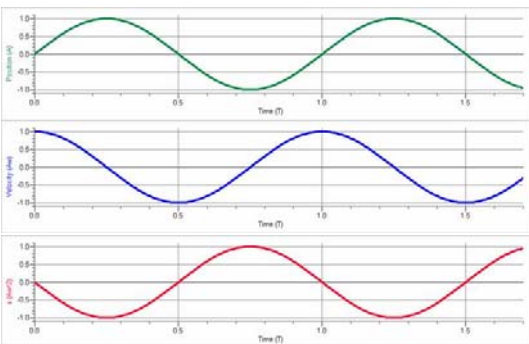
Conditions Required for SHM

- The acceleration causing the motion is proportional to the displacement of the object from its equilibrium position
- The accelerating force must be trying to restore the object to its equilibrium position

$$a \propto -x$$



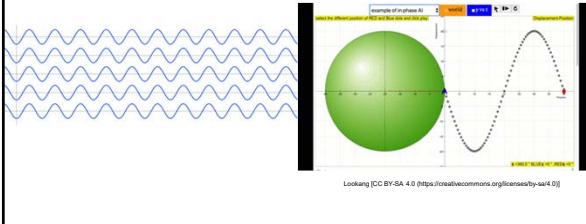
Graphing SHM



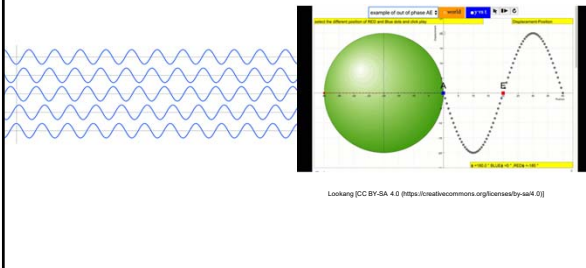
farragutn.com/science/milligan/apphys/shmover.htm

Phase Difference

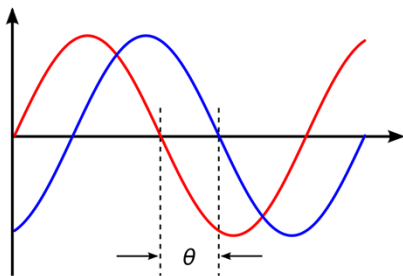
- When waves have the same frequency and starting point they are said to be in phase

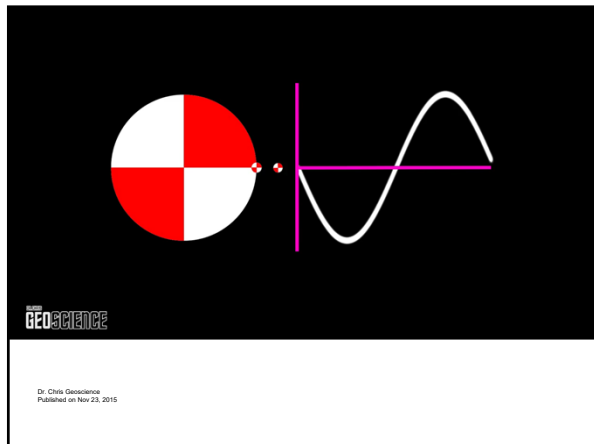


- When waves of the same frequency have different starting points they are said to be out of phase



- The difference between starting points between waves that are out of phase is the phase difference or phase shift (measured in degrees or radians)





SHM and Circular Motion

- SHM is related to circular motion
- An object moving in a circle with constant angular velocity has an angular displacement given by $\theta = \omega t$

- The projection of the y component of the motion at a given time is $y = r \sin \theta$ or equivalently $y = r \sin \omega t$

Displacement, Velocity, & Acceleration

- Displacement can be represented by the equation:

$$x = x_0 \sin \omega t$$

- An equation for the velocity can be found by taking the derivative (calculus) of the displacement giving:

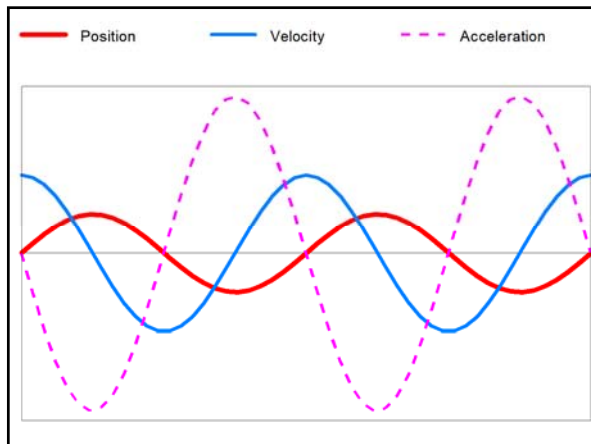
$$v = \omega x_0 \cos \omega t$$

- The acceleration will be the derivative of the velocity:

$$a = -\omega^2 x_0 \sin \omega t$$

- But $x = x_0 \sin \omega t$

$$a = -\omega^2 x$$



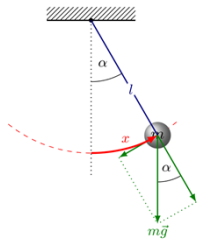
The Velocity Equation

- We can derive an equation for the velocity of the particle at a given point

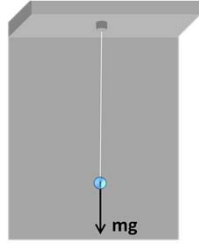
$$v = \pm \omega \sqrt{(x_0^2 - x^2)}$$

Simple Pendulum

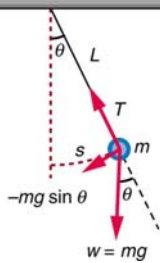
- The restoring force is perpendicular to the pendulum bob and string



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<https://openstax.org/r/physicsbook2/chapter-the-simple-pendulum/>

$$-mg \sin \theta = ma$$

$$\sin \theta = \frac{x}{l}$$

x – displacement in x direction
 l – length of pendulum

$$a = -\frac{gx}{l}$$

- This looks like the defining equation of SHM

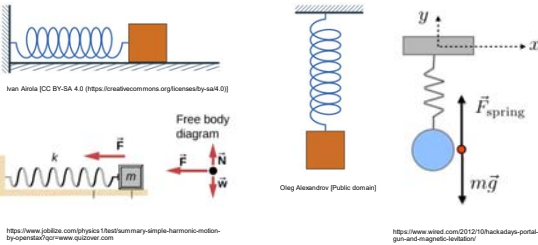
$$a = -\left(\frac{g}{l}\right)x \qquad a = -\omega^2 x$$

- Therefore... $\omega^2 = \frac{g}{l}$
- Since the period for SHM is given by $T = \frac{2\pi}{\omega}$ the period of the pendulum is

$$T = 2\pi \sqrt{\frac{l}{g}}$$

Mass and Spring

- The restoring force for a mass on a spring is $F = -kx$



$$-kx = ma$$

$$a = -\left(\frac{k}{m}\right)x$$

- Comparing this to the defining equation of SHM gives

$$\omega^2 = \frac{k}{m}$$

- And therefore a period of $T = 2\pi \sqrt{\frac{m}{k}}$

Energy

- A moving object has a kinetic energy of
 $E_k = \frac{1}{2}mv^2$
- The velocity of a particle in SHM at a given point is $v = \pm\omega\sqrt{x_0^2 - x^2}$
- Combining these equations gives us the kinetic energy at displacement x

$$E_k = \frac{1}{2}m\omega^2(x_0^2 - x^2)$$

- The maximum kinetic energy occurs when the displacement is zero

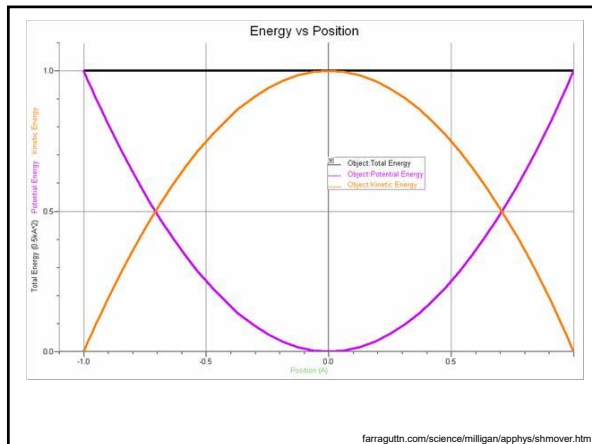
$$E_{k_{max}} = \frac{1}{2}m\omega^2x_0^2$$

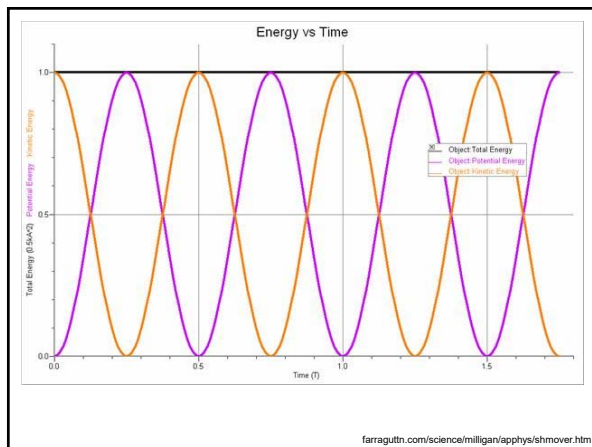
- This must be the total energy (as the potential energy at this point is zero)

$$E_T = \frac{1}{2}m\omega^2x_0^2$$

- We can calculate the potential energy by subtracting kinetic energy from the total energy

$$E_p = E_T - E_k = \frac{1}{2}m\omega^2x_0^2 - \frac{1}{2}m\omega^2(x_0^2 - x^2) = \frac{1}{2}m\omega^2x^2$$

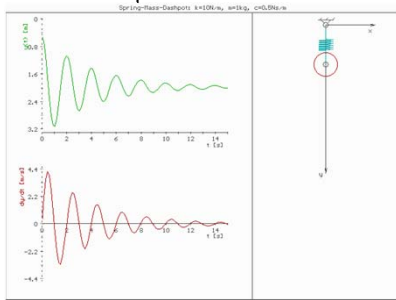




Damping

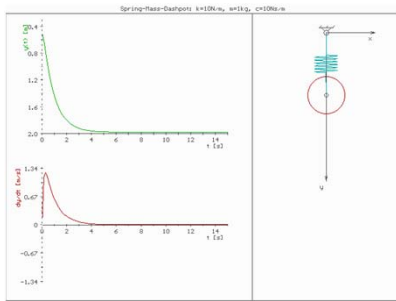
- All mechanical systems will vibrate when they are set in motion
- If a system is allowed to vibrate without any external forces being applied, it will vibrate at its natural frequency, f_0
- When resistive forces are present then the vibrations decay
- This is referred to as damping

- Underdamping
 - the amplitude gradually decreases until the oscillations stop



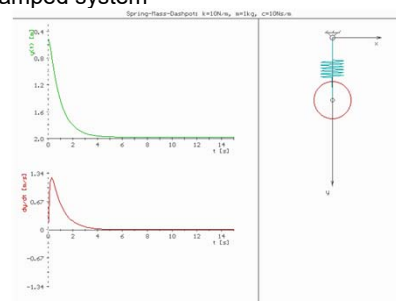
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- Critical damping
 - The system returns to equilibrium in the shortest time possible with no oscillations

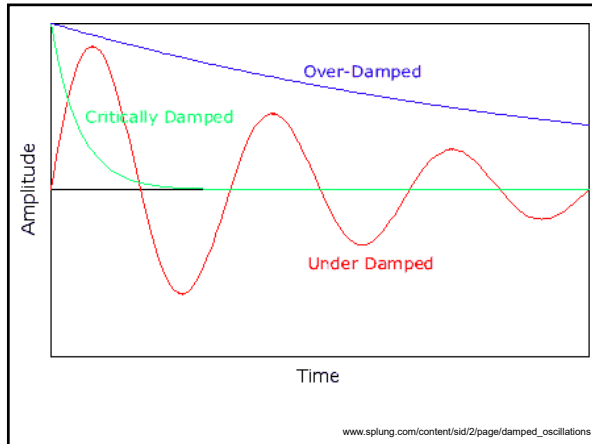


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- Overdamping
 - The system returns to equilibrium with no oscillations but much slower than a critically damped system



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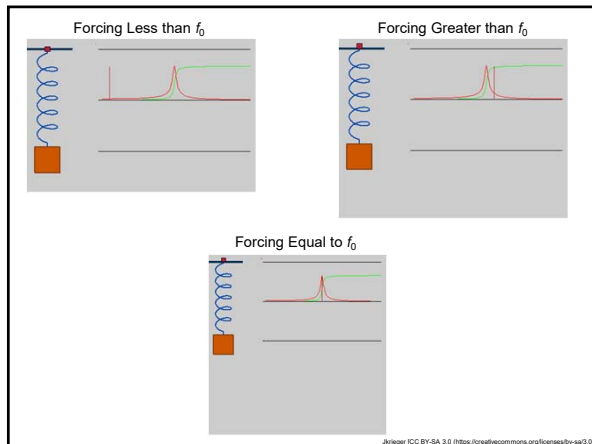


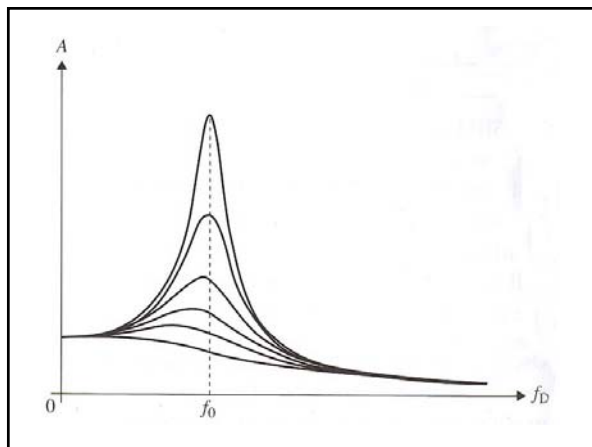
Forced Vibrations

- When an external force acts on a mechanical system, the force may have its own frequency of vibration, which may affect the motion of the mechanical system
- Forced vibrations are those that occur when a regularly changing external force is applied to a system resulting in the system vibrating at the same frequency as the force

Resonance

- When a mechanical system is forced to oscillate by a driving force that has the same frequency as the natural frequency (f_0) of the mechanical system, it will vibrate with maximum amplitude.
- This is called resonance.
- The degree of damping will alter the amplitude response of the system.





Q factor

- The Q or “quality” factor is a criterion by which the sharpness of resonance can be assessed.

$$Q = 2\pi \frac{\text{energy stored}}{\text{energy dissipated per cycle}}$$

$$Q = 2\pi \times \text{resonant frequency} \times \frac{\text{energy stored}}{\text{power loss}}$$

- The Q factor is a numerical value with no units
- A system with a high Q factor is lightly damped
 - Energy dissipated per cycle is small
- The larger the Q factor, the sharper the resonance peak
- The Q factor is approximately the number of oscillations the system will make before its amplitude will decay to zero

- Some typical Q factors

Oscillator	Q factor
critically damped door	0.5
mass on spring	50
simple pendulum	200
oscillating quartz crystal	30 000

Resonance can be bad...



Resonance can also be good...

- Microwave ovens
 - Microwaves force oscillation of water molecules generating heat inside the food
- Radios
 - The tuner uses resonance to select the station
- Quartz oscillators
 - The quartz is forced with an electric current causing it to oscillate at a very specific frequency
